

# Primal-Dual Hybrid Gradient algorithm Preconditioning

**Evangelos Papoutsellis**

University of Manchester

evangelos.papoutsellis@manchester.ac.uk

CCPi/SyneRBI vhackathon

June 2020



# Primal-Dual Hybrid Gradient (PDHG) algorithm

$$x^* \in \arg \min_{x \in X} \mathcal{F}(Kx) + \mathcal{G}(x) \quad (1)$$

- ①  $X, Y$  finite dimensional vector spaces,  $K : X \rightarrow Y$  is a linear operator.
- ②  $\mathcal{F}, \mathcal{G}$  proper, convex & lower-semicontinuous.
- ③  $\mathcal{G} : X \rightarrow [0, \infty), \mathcal{F} : Y \rightarrow [0, \infty)$

## Examples

$$\arg \min_{u \in X} \left\{ \alpha \text{TV}(u) + \frac{1}{2} \|Au - g\|_2^2 \right\} \quad (2)$$

$$\arg \min_{u \in X} \left\{ \alpha \text{TV}(u) + \sum Au - g \log(Au + \eta) + \mathbb{I}_{\{u > 0\}}(u) \right\} \quad (3)$$

- ①  $\text{TV}(u) := \|\nabla u\|_{2,1} = \sum \sqrt{(\partial_x u)^2 + (\partial_y u)^2}$
- ②  $g$ : Acquisition Data
- ③  $\alpha$ : Regularising parameter
- ④  $A$ : Projection operator

# Primal-Dual Hybrid Gradient (PDHG) algorithm

**PDHG** algorithm solves non-smooth convex optimization problems with *saddle-point* structure:

$$\min_{x \in X} \max_{y \in Y} \langle Kx, y \rangle - \mathcal{F}^*(y) + \mathcal{G}(x)$$

$$\min_{x \in X} \left\{ \mathcal{F}(Kx) + \mathcal{G}(x) \right\} \quad (\text{Primal problem})$$

$$\max_{y \in Y} \left\{ -\mathcal{G}^*(-K^*y) - \mathcal{F}^*(y) \right\} \quad (\text{Dual problem})$$

$\mathcal{F}^*$ ,  $\mathcal{G}^*$  convex conjugates of functionals  $\mathcal{F}$ ,  $\mathcal{G}$ .

- $(x^*, y^*)$  is a saddle point, i.e.,

$$\mathcal{L}(x^*, y) \leq \mathcal{L}(x^*, y^*) \leq \mathcal{L}(x, y^*), \forall (x, y) \in X \times Y$$

for  $\mathcal{L}(x, y) := \langle Kx, y \rangle - \mathcal{F}^*(y) + \mathcal{G}(x)$ .

- $(x^*, y^*)$  is a saddle point  $\Rightarrow x^*$  is a solution of the Primal Problem,  $y^*$  is a solution of the Dual problem.
- *Primal-Dual Gap*  $:= \mathcal{F}(Kx) + \mathcal{G}(x) + \mathcal{G}^*(-K^*y) + \mathcal{F}^*(y) \geq 0$
- If  $(x^*, y^*)$  is a saddle point then *PDgap* vanishes.

# Primal-Dual Hybrid Gradient (PDHG) algorithm

## PDHG ( or Chambolle-Pock) algorithm

- $(x^0, y^0) \in (X \times Y)$ ,  $\bar{x}^0 = x^0$ .
- $\tau, \sigma > 0$  ( stepsize parameters) such that  $\tau\sigma\|K\|^2 < 1$ ,  $\theta \in [0, 1]$ .
- $\|K\| = \sup \left\{ \|Kx\| : \|x\| \leq 1 \right\}$ .

### Update:

- $y^{n+1} = (I + \sigma\partial F^*)^{-1}(y^n + \sigma K\bar{x}^n)$  ( Gradient ascend dual variable )
- $x^{n+1} = (I + \tau\partial G)^{-1}(x^n - \tau K^* \bar{y}^{n+1})$  ( Gradient descent primal variable )
- $\bar{x}^{n+1} = x^{n+1} + \theta(x^{n+1} - x^n)$  (Over-relaxation step)

$$\begin{aligned}(I + \sigma\partial F^*)^{-1}(y) &:= \arg \min_{z \in Y} \left\{ \frac{1}{2} \|y - z\|^2 + \sigma \mathcal{F}^*(z) \right\} =: \text{prox}_{\sigma \mathcal{F}^*}(y) \\(I + \tau\partial G)^{-1}(x) &:= \arg \min_{z \in X} \left\{ \frac{1}{2} \|x - z\|^2 + \tau \mathcal{G}(z) \right\} =: \text{prox}_{\tau \mathcal{G}}(x)\end{aligned}\tag{4}$$

**Assumption:** Proximal operators are "easy to solve", i.e. have closed form solution or can be efficiently computed with a high precision.

# Primal-Dual Hybrid Gradient (PDHG) algorithm

- PDHG is a powerful and flexible algorithm with simple subproblems to solve.
- Requires careful choice of stepsize parameters  $(\sigma, \tau)$  to accelerate convergence e.g.,  $(\sigma, \tau) = (\frac{1}{\|K\|}, \frac{1}{\|K\|})$ ,  $(\sigma, \tau) = (10, \frac{1}{\sigma\|K\|^2})$ 
  - Tradeoff between primal & dual residuals. Large  $\tau$  value  $\Rightarrow$  Strong minimization step in the primal variable  $\Rightarrow$  Slow maximization in the dual variable.
- $\sigma, \tau$  depends on  $\|K\|$  which in practice cannot be computed exactly  $\Rightarrow$  **Power iteration**. Large operator norm  $\Rightarrow$  Slow convergence.

## Alternatives

- Adaptive update  $(\sigma, \tau)$  based on (convex) properties of  $\mathcal{F}^*, \mathcal{G}$ .<sup>1</sup>
- Adaptive update  $(\sigma, \tau)$  based on primal & dual residuals.<sup>2</sup>
- Preconditioning PDHG  $\Rightarrow$  Replace scalars  $\tau, \sigma$  by  $T, \Sigma$  symmetric and positive definite matrices.<sup>3</sup>

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<sup>1</sup> Chambolle and Pock 2010, <sup>2</sup> Goldstein, Li, Yuan, Esser, Baraniuk, 2015, <sup>3</sup> Chambolle and Pock 2011, Pock, Cremers, Bischof, Chambolle 2009, Esser, Zhang, Chan, 2010

## PDHG

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- $\tau, \sigma > 0$  (stepsize parameters) such that  $\tau\sigma\|K\|^2 < 1$ ,  $\theta \in [0, 1]$ .

### Update:

- $y^{n+1} = (I + \sigma\partial F^*)^{-1}(y^n + \sigma K\bar{x}^n)$
- $x^{n+1} = (I + \tau\partial G)^{-1}(x^n - \tau K^* \bar{y}^{n+1})$
- $\bar{x}^{n+1} = x^{n+1} + \theta(x^{n+1} - x^n)$

## Preconditioning - PDHG

- $(x^0, y^0) \in (X \times Y)$ ,  $\bar{x}^0 = x^0$ .
- $\Sigma, \mathbf{T}$  (symmetric, positive definite matrices) such that  $\|\Sigma^{1/2} \mathbf{K} \mathbf{T}^{1/2}\|^2 < 1$ ,  $\theta = 1$ .

### Update:

- $y^{n+1} = (I + \Sigma \partial F^*)^{-1}(y^n + \Sigma K \bar{x}^n)$
- $x^{n+1} = (I + \mathbf{T} \partial G)^{-1}(x^n - \mathbf{T} K^* \bar{y}^{n+1})$
- $\bar{x}^{n+1} = x^{n+1} + \theta(x^{n+1} - x^n)$

$$(I + \Sigma \partial F^*)^{-1}(y) := \arg \min_{z \in Y} \left\{ \frac{1}{2} \|y - z\|_{\Sigma}^2 + \mathcal{F}^*(z) \right\}, \quad (5)$$

where,

$$\|x\|_{\Sigma}^2 := \|\Sigma^{-1/2} x\|^2 = \langle \Sigma^{-1} x, x \rangle.$$

## Preconditioning - PDHG

- $(x^0, y^0) \in (X \times Y)$ ,  $\bar{x}^0 = x^0$ .
- $\Sigma, \mathbf{T}$  (symmetric, positive definite matrices) such that  $\|\Sigma^{1/2} \mathbf{K} \mathbf{T}^{1/2}\|^2 < 1$ ,  $\theta = 1$ .

### Update:

- $y^{n+1} = (I + \Sigma \partial F^*)^{-1}(y^n + \Sigma K \bar{x}^n)$
- $x^{n+1} = (I + \mathbf{T} \partial G)^{-1}(x^n - \mathbf{T} K^* \bar{y}^{n+1})$
- $\bar{x}^{n+1} = x^{n+1} + \theta(x^{n+1} - x^n)$

**Choice of preconditioners:** Let  $a \in [0, 2]$ ,  $\mathbf{T} = \text{diag}(\tau)$ ,  $\Sigma = \text{diag}(\sigma)$

$$\tau = (\tau_j)_{1 \leq j \leq n} = \frac{1}{\sum_{i=1}^m |K_{i,j}|^{2-a}}, \quad j = 1, \dots, n \quad (\text{Sum over columns})$$
$$\sigma = (\sigma_i)_{1 \leq i \leq m} = \frac{1}{\sum_{j=1}^n |K_{i,j}|^a}, \quad i = 1, \dots, m \quad (\text{Sum over rows})$$
(5)



# Example: (Precond) PDHG

$$\arg \min_{u \in X} \left\{ \alpha \|\nabla u\|_{2,1} + \sum Au - g \log(Au + \eta) + \mathbb{I}_{\{u>0\}}(u) \right\}$$
$$\Updownarrow$$
$$\arg \min_{x \in X} \mathcal{F}(Kx) + \mathcal{G}(x) \quad (6)$$

## (Explicit) PDHG

$$K = \begin{bmatrix} \nabla \\ A \end{bmatrix}, \quad \mathcal{G}(x) := \mathcal{G}(u) = \mathbb{I}_{\{u>0\}}(u), \quad \sigma = \tau = \frac{1}{\|K\|}$$

$$\mathcal{F}(z) = \sum_{i=1}^2 F_i(z_i) := \alpha \|z_1\|_{2,1} + \sum z_2 - g \log(z_2 + \eta) \quad (\text{Separable Sum})$$

$$\text{prox}_{\tau \mathcal{G}}(\hat{u}) = \max \{\hat{u}, 0\}$$

$$\text{prox}_{\sigma \mathcal{F}^*}(\hat{z}) = \begin{bmatrix} \text{prox}_{\sigma F_1^*}(\hat{z}_1) = \frac{\hat{z}_1}{\max \{1, \frac{|\hat{z}_1|_2}{\alpha}\}} \\ \text{prox}_{\sigma F_2^*}(\hat{z}_2) = 0.5 \left( \hat{z}_2 + \sigma \eta + 1 - \sqrt{(\hat{z}_2 + \sigma \eta - 1)^2 + 4\sigma g} \right) \end{bmatrix}$$

# Example: (Precond) PDHG

$$\arg \min_{u \in X} \left\{ \alpha \|\nabla u\|_{2,1} + \sum Au - g \log(Au + \eta) + \mathbb{I}_{\{u>0\}}(u) \right\}$$
$$\updownarrow$$
$$\arg \min_{x \in X} \mathcal{F}(Kx) + \mathcal{G}(x) \quad (6)$$

## (Explicit) Precond-PDHG

$$K = \begin{bmatrix} \nabla \\ A \end{bmatrix}, \quad \mathcal{G}(x) := \mathcal{G}(u) = \mathbb{I}_{\{u>0\}}(u), \quad \Sigma, \mathbf{T} : \text{(Diagonal Matrices)}$$

$$\mathcal{F}(z) = \sum_{i=1}^2 F_i(z_i) := \alpha \|z_1\|_{2,1} + \sum z_2 - g \log(z_2 + \eta) \quad (\text{Separable Sum})$$

$$\text{prox}_{\mathbf{T}\mathcal{G}}(\hat{u}) = \max\{\hat{u}, 0\}$$

$$\text{prox}_{\Sigma\mathcal{F}^*}(\hat{z}) = \begin{bmatrix} \text{prox}_{\Sigma_1 F_1^*}(\hat{z}_1) = \frac{\hat{z}_1}{\max\{1, \frac{|\hat{z}_1|_2}{\alpha}\}} \\ \text{prox}_{\Sigma_2 F_2^*}(\hat{z}_2) = 0.5 \left( \hat{z}_2 + \Sigma_2 \eta + 1 - \sqrt{(\hat{z}_2 + \Sigma_2 \eta - 1)^2 + 4\Sigma_2 g} \right) \end{bmatrix}$$

# Example: (Precond) PDHG

$$\arg \min_{u \in X} \left\{ \alpha \|\nabla u\|_{2,1} + \sum Au - g \log(Au + \eta) + \mathbb{I}_{\{u>0\}}(u) \right\} \quad (6)$$
$$\Updownarrow$$
$$\arg \min_{x \in X} \mathcal{F}(Kx) + \mathcal{G}(x)$$

(Explicit) PDHG  $\Rightarrow$  in CIL

```
1 op1 = Gradient(ig)
2 op2 = AstraProjectorSimple(ig, ag)
3 K = BlockOperator(op1, op2)
4
5 f = BlockFunction(alpha * MixedL21Norm(),
6                   KullbackLeibler(b=noisy_data, eta = eta))
7
8 normK = K.norm()
9 sigma = 1/normK
10 tau = 1/normK
11
12 pdhg = PDHG(f = f, g = g, operator = K, tau = tau, sigma = sigma,
13            max_iteration = 1000, update_objective_interval = 200)
14 pdhg.run(very_verbose = True)
```

# Example: (Precond) PDHG

$$\arg \min_{u \in X} \left\{ \alpha \|\nabla u\|_{2,1} + \sum Au - g \log(Au + \eta) + \mathbb{I}_{\{u>0\}}(u) \right\}$$
$$\Downarrow$$
$$\arg \min_{x \in X} \mathcal{F}(Kx) + \mathcal{G}(x) \tag{6}$$

## (Implicit) PDHG

$$K = A, \quad \mathcal{G}(x) := \mathcal{G}(u) = \alpha \|\nabla u\|_{2,1} + \mathbb{I}_{\{u>0\}}(u), \quad \mathcal{F}(z) = \sum z - g \log(z + \eta)$$

$$\text{prox}_{\sigma F_2^*}(\hat{z}) = 0.5 \left( \hat{z} + \sigma \eta + 1 - \sqrt{(\hat{z} + \sigma \eta - 1)^2 + 4\sigma g} \right) \tag{7}$$

$$\text{prox}_{\tau(\alpha \|\nabla(\cdot)\|_{2,1})}(\hat{u}) = \arg \min_{u>0} \left\{ \frac{1}{2} \|u - \hat{u}\|^2 + \alpha \|\nabla u\|_{2,1} \right\} \tag{8}$$

$\Rightarrow$  Solve using **Fast Gradient Projection** (FGP) algorithm.\*

## Example: (Precond) PDHG

$$\arg \min_{u \in X} \left\{ \alpha \|\nabla u\|_{2,1} + \sum Au - g \log(Au + \eta) + \mathbb{I}_{\{u>0\}}(u) \right\}$$
$$\Updownarrow$$
$$\arg \min_{x \in X} \mathcal{F}(Kx) + \mathcal{G}(x) \tag{6}$$

### **(Implicit) Precond - PDHG**

$K = A$ ,  $\mathcal{G}(x) := \mathcal{G}(u) = \alpha \|\nabla u\|_{2,1} + \mathbb{I}_{\{u>0\}}(u)$ ,  $\mathcal{F}(z) = \sum z - g \log(z + \eta)$

Since,  $K$  is a positive operator, i.e.,  $Kx \geq 0$ ,  $\forall x \geq 0$ , for  $a = 1$ , we have:

$$\Sigma = \frac{1}{K\mathbf{1}_X}, \quad \mathbf{T} = \frac{1}{K^T\mathbf{1}_Y}$$

$$\text{prox}_{\Sigma F_2^*}(\hat{z}) = 0.5 \left( \hat{z} + \Sigma \eta + 1 - \sqrt{(\hat{z} + \Sigma \eta - 1)^2 + 4\Sigma g} \right) \tag{7}$$

$$\text{prox}_{\mathbf{T}(\alpha \|\nabla(\cdot)\|_{2,1})}(\hat{u}) = \arg \min_{u>0} \left\{ \frac{1}{2} \|u - \hat{u}\|_{\mathbf{T}}^2 + \alpha \|\nabla u\|_{2,1} \right\} \tag{8}$$

$\Rightarrow$  Solve using **Fast Gradient Projection** (FGP) algorithm.\*

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\* Beck, Teboulle 2009

# Example: (Precond) PDHG

$$\arg \min_{u \in X} \left\{ \alpha \|\nabla u\|_{2,1} + \sum Au - g \log(Au + \eta) + \mathbb{I}_{\{u>0\}}(u) \right\}$$

$\Updownarrow$

$$\arg \min_{x \in X} \mathcal{F}(Kx) + \mathcal{G}(x)$$
(6)

## (Implicit) PDHG

```
1 K = AstraProjectorSimple(ig, ag)
2
3 f = KullbackLeibler(b = noisy_data, eta = eta)
4 g = TotalVariation(alpha, num_iters, lower = 0)
5
6 if precondition:
7     tau = 1/K.adjoint(K.range_geometry().allocate(1))
8     sigma = 1/K.direct(K.domain_geometry().allocate(1))
9 else:
10    normK = K.norm()
11    sigma = 1/normK
12    tau = 1/normK
13
14 pdhg = PDHG(f = f, g = g, operator = K, tau = tau, sigma = sigma,
15            max_iteration = 1000, update_objective_interval = 200)
16 pdhg.run(very_verbose = True)
```

Thank you for your attention